

Algebraic Calculi for Hybrid Systems

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Hybrid Systems

Definition

hybrid systems are heterogeneous systems characterised by the interaction of *discrete* and *continuous* dynamics

Applications

- (air-)traffic controls / traffic management
- chemical and biological processes
- automated manufacturing
- ...

Kinds of Systems

Transformational Systems

determine a function

Reactive Systems

interact with environment

Real-Time Systems

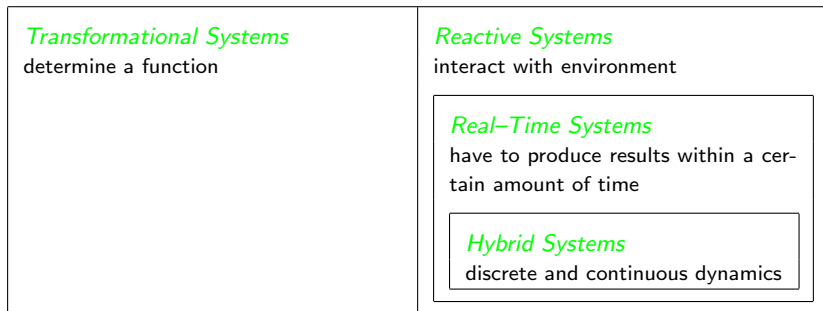
have to produce results within a certain amount of time

Hybrid Systems

discrete and continuous dynamics

source: University of Oldenburg

Kinds of Systems



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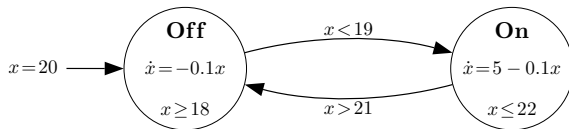
**less than 1% of all processors are in PCs;
more than 98% are controllers of hybrid systems**

Hybrid Automata

- most common representation type for hybrid systems
- widely popular for designing and modelling
- similar to finite state machines
- states describe continuous dynamics
- edges describe discrete behaviours

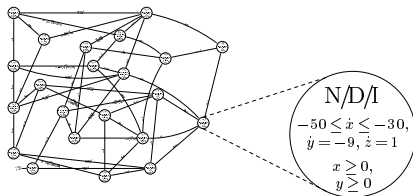
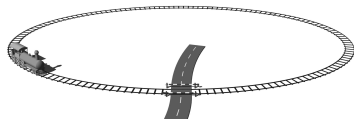
Example

Gas Burner:



Example

Railway Crossing:



- gate must be closed, if train passes

Hybrid Automata

(Dis-)Advantages

- easy to construct/understand
- growing fast and becoming unreadable
- nearly impossible to check **liveness** or **safety**
(only done partly for a small class of hybrid systems)
- nearly no software-tools available

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Question/Idea

is there a relation to an algebra like the relationship between finite statemachines, regular languages and Kleene algebra

Towards an Algebra of Hybrid Systems

Questions

- what are possible elements
- how to describe discrete and continuous behaviour
- how to describe infinity
(interaction on an on-going, nearly never-ending basis)
- how to compose elements
- how to choose between elements

Towards an Algebra of Hybrid Systems

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Possible Answers

- elements are trajectories
- continuous behaviour is described by the flow functions
- discrete behaviours are e.g. jumps in the function
- algebra is based on sets of trajectories
- weak Kleene algebra allows modelling infinite elements

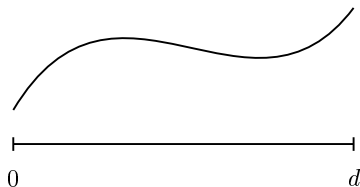
Trajectories

Definition

a **trajectory** t is a pair (d, g) , where $d \in D$ is the **duration** and

$$g : [0, d] \rightarrow V \text{ or } g : [0, \infty) \rightarrow V$$

the image of $[0, d]$ ($[0, \infty)$) under g is its **range** $\text{ran}(d, g)$

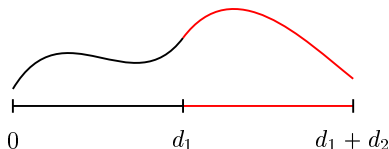


D has to fulfil some properties

Composition of Trajectories

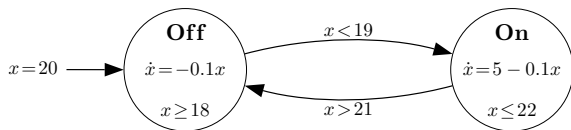
$$(d_1, g_1) \cdot (d_2, g_2) =_{af} \begin{cases} (d_1 + d_2, g) & \text{if } d_1 \neq \infty \wedge g_1(d_1) = g_2(0) \\ (d_1, g_1) & \text{if } d_1 = \infty \\ \text{undefined} & \text{otherwise} \end{cases}$$

with $g(x) = g_1(x)$ for all $x \in [0, d_1]$ and $g(x + d_1) = g_2(x)$ for all $x \in [0, d_2]$ or $x \in [0, \infty)$

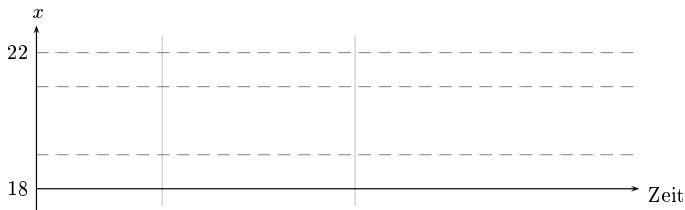


Connection to Hybrid Automata

a trajectory can model a run of a hybrid automaton

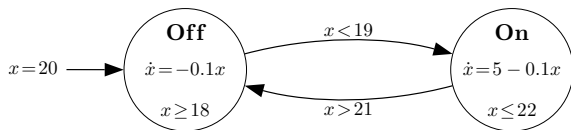


trajectory



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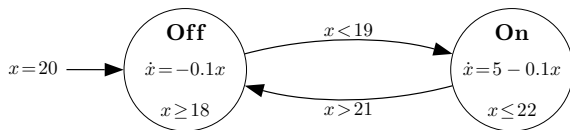


trajectory

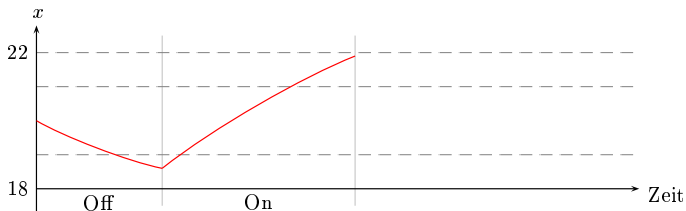


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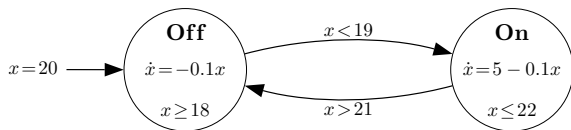


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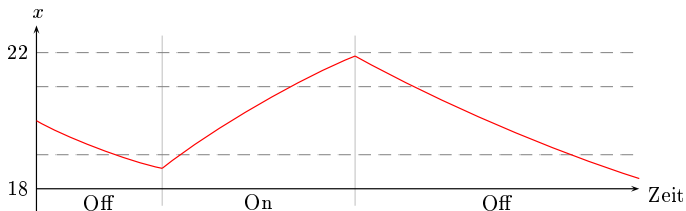


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trajectory



Getting Algebraic

the algebraic model of regular events is Kleene algebra

Definition

a **Kleene algebra** is a tuple $(K, +, 0, \cdot, 1, *)$ with

- $(K, +, 0)$ idempotent commutative monoid
- $(K, \cdot, 1)$ monoid
- multiplication is distributive
- 0 is an annihilator, $0 \cdot a = 0 = a \cdot 0$
- $*$ satisfies **unfold** and **induction** axioms

$+$ \leftrightarrow choice

\cdot \leftrightarrow sequential composition

$*$ \leftrightarrow finite iteration

0 \leftrightarrow abort

1 \leftrightarrow skip

Choice, Composition and Neutral Elements

- choice between trajectories is realised by set union over **sets of trajectories** (also called processes)
- the empty set is neutral element
- composition is lifted pointwise to processes

$$A \cdot B =_{df} \inf A \cup \{a \cdot b \mid a \in \text{fin } A, b \in B, a \cdot b \text{ is defined}\}$$

- the set of all trajectories with duration 0 (denoted by $\mathbb{1}$) is the neutral element

the algebra of hybrid systems $(\mathcal{P}(\text{TRA}), \cup, \emptyset, \cdot, \mathbb{1}, *)$ is nearly a Kleene algebra (TRA is the set of all trajectories)

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But

$$A \cdot \emptyset \neq \emptyset$$

Weak Kleene Algebra

Definition

a **weak Kleene algebra** is a Kleene algebra where 0 is only left annihilator ($0 \cdot a = 0$)

Remark

- relaxation allows to have infinite elements [Möller04]

$$\text{inf } a = a \cdot 0 \quad \text{fin } a = a - \text{inf } a$$

- weak Kleene algebra behaves nearly like Kleene algebra
- adding infinite iteration yields weak omega algebra [Cohen00]
- adding tests to model assertions and guards [Kozen97]
- adding domain/codomain [DesharnaisMöllerStruth03]
- in some situations one even needs no right-distributivity law
- weak Kleene algebra generalises predicate transformers [vonWright02]

Remarks on the Algebra of Hybrid Systems

- similarities to function spaces (linear algebra)
- if $D = \{0, 1\}$ then the algebra of hybrid systems is equivalent to relations
- jumps at composition points possible
- restricted form of composition

$$A \frown B = (\text{fin } A) \cdot B$$

the second trajectory is reached

- can be endowed with tests and domain functions.

Safety and Liveness

Safety: “something bad will never happen” [Lamport77]

- conservative in the sense of avoiding bad states
- e.g. do nothing
- something is true forever

Liveness: “something good will eventually happen” [Lamport77]

- progressive in the sense of reaching good states
or the system will never stop

Algebraic Safety and Liveness

Examples for Range-Restriction Operators

- P will be reached

$$\diamond P =_{df} F \cdot P \cdot \top$$

set of all trajectories, where the range is within P at some point

- P is guaranteed

$$\square P =_{df} \overline{\diamond \neg P}$$

set of all trajectories, where the range is complete in P
needs complementation on underlying structure

\top is the set of *all* trajectories;

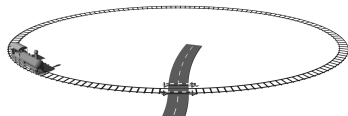
F is the set of *all finite* trajectories;

P is a set of trajectories *without* duration.

Basic Properties

- $\Box P \sqcap A \cdot B = (\Box P \sqcap A) \cdot (\Box P \sqcap B)$
- $\Diamond P \sqcap A \cdot B = (\Diamond P \sqcap A) \cdot B + \text{fin } A \cdot (\Diamond P \sqcap B)$
- $(\Box P) \cdot (\Box P) = \Box P$

Example



$$(O \parallel (P_1 \cdot T_1 \cdot P_2)) \cdot \left(((M_1 \cdot C) \parallel (T_2 \cdot P_3)) \cdot (C \parallel (T_2 \cdot P_4) \approx) \cdot ((M_2 \cdot O) \parallel (T_1 \cdot P_2)) \right)^\omega$$

- algebraic description
- off-the-shelf theorem provers can be used

Example



$$\begin{aligned}
 & (O \parallel (P_1 \cdot T_1 \cdot P_2)) \cdot \left(((M_1 \cdot C) \parallel (T_2 \cdot P_3)) \cdot \right. \\
 & \left. (C \parallel (T_2 \cdot P_4) \approx) \cdot ((M_2 \cdot O) \parallel (T_1 \cdot P_2)) \right)^\omega
 \end{aligned}$$

- algebraic description
- off-the-shelf theorem provers can be used

Important Algebraic Term

$$P_1 \cdot T \cdot P_2$$

pre- and postconditions

- if P_1 is satisfied, then P_2 holds after the execution of T
- closely related to “If-then-constructs” (logic)

Algebraic Logic

logics can be embedded in the same algebraic framework

- Hoare logic [Kozen97,MöllerStruth06]
- Duration Calculus [Hoefner03]
- LTL [DesharnaisMöllerStruth04]
- CTL and CTL* [MöllerHöfnerStruth06]
- Neighbourhood Logic of Zhou and Hansen [Höfner06]

Advantages

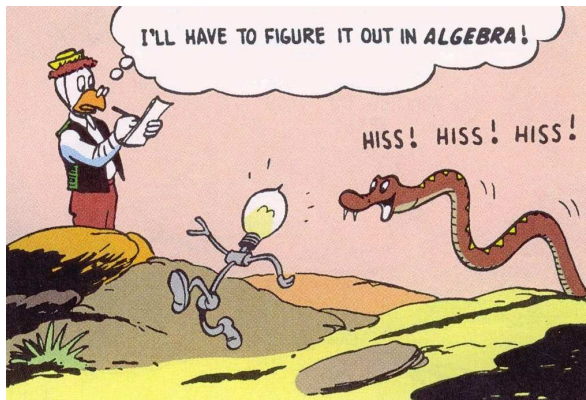
- knowledge transfer
in CTL, CTL* there are notions of liveness, safety, ...
- use of standard terminology
- support of computers

Conclusion

- build an algebra of hybrid systems
- show basic properties
- characterise different useful modal operators in the setting
- give useful embeddings for logics

(Dis)Advantages

- create a “uniform” basis
- algebraic structures like Kleene algebra are well known
- algebra allows easy calculations
- but sometimes domain-knowledge is needed
- not easy to understand (especially for non-computer scientists)
- aid of computer is feasible (Prover9) [HöfnerStruth07, Höfner08]



If you are faced by a difficulty or a controversy in science,
an ounce of algebra is worth a ton of verbal argument.

J.B.S. Haldane